San Pablo Catholic University (UCSP) Undergraduate Program in Computer Science SILABO



CS261. Artificial intelligence (Mandatory)

1. General information

1.1 School : Ciencia de la Computación 1.2 Course : CS261. Artificial intelligence

1.3 Semester : 7^{mo} Semestre.

1.4 Prerrequisites : MA203. Statistics and Probability. (4^{th} Sem)

1.5 Type of course : Mandatory 1.6 Learning modality : Blended

1.7 Horas : 2 HT; 2 HP; 2 HL;

1.8 Credits : 4

2. Professors

Lecturer

- Juan Carlos Gutiérrez Cáceres < jcgutierrezc@ucsp.edu.pe>
 - PhD in Ciencia de la Computación, Universidad Nacional de San Agustín, Perú, 2013.
 - MSc in Ciencia de la Computación, ICMC-USP, Brasil, 2003.

3. Course foundation

Research in Artificial Intelligence has led to the development of numerous relevant tonic, aimed at the automation of human intelligence, giving a panoramic view of different algorithms that simulate the different aspects of the behavior and the intelligence of the human being.

4. Summary

1. Fundamental Issues 2. Agents 3. Basic Search Strategies 4. Advanced Search 5. Reasoning Under Uncertainty 6. Basic Machine Learning 7. Advanced Machine Learning 8. Natural Language Processing 9. Perception and Computer Vision

5. Generales Goals

- Evaluate the possibilities of simulation of intelligence, for which the techniques of knowledge modeling will be studied.
- Build a notion of intelligence that later supports the tasks of your simulation.

6. Contribution to Outcomes

This discipline contributes to the achievement of the following outcomes:

- a) An ability to apply knowledge of mathematics, science. (Usage)
- h) A recognition of the need for, and an ability to engage in life-long learning. (Familiarity)
- i) An ability to use the techniques, skills, and modern computing tools necessary for computing practice. (Familiarity)
- j) Apply the mathematical basis, principles of algorithms and the theory of Computer Science in the modeling and design of computational systems in such a way as to demonstrate understanding of the equilibrium points involved in the chosen option. (Familiarity)

7. Content

Competences: a		
Content	Generales Goals	
 Overview of AI problems, examples of successful recent AI applications What is intelligent behavior? The Turing test Rational versus non-rational reasoning Problem characteristics Fully versus partially observable Single versus multi-agent Deterministic versus stochastic Static versus dynamic Discrete versus continuous Nature of agents Autonomous versus semi-autonomous Reflexive, goal-based, and utility-based The importance of perception and environmental interactions Philosophical and ethical issues. 	 Describe Turing test and the "Chinese Room" thought experiment [Usage] Determing the characteristics of a given problem that an intelligent systems must solve [Usage] 	

Competences: a Content Generales Goals • Definitions of agents • List the defining characteristics of an intelligent agent [Usage] • Agent architectures (e.g., reactive, layered, cogni-• Characterize and contrast the standard agent architectures [Usage] • Agent theory • Describe the applications of agent theory to domains • Rationality, game theory such as software agents, personal assistants, and believable agents [Usage] - Decision-theoretic agents - Markov decision processes (MDP) • Describe the primary paradigms used by learning agents [Usage] • Software agents, personal assistants, and information access • Demonstrate using appropriate examples how multiagent systems support agent interaction [Usage] - Collaborative agents - Information-gathering agents - Believable agents (synthetic characters, modeling emotions in agents) • Learning agents • Multi-agent systems - Collaborating agents - Agent teams - Competitive agents (e.g., auctions, voting) - Swarm systems and biologically inspired models Readings: Nilsson (2001), Russell and Norvig (2003), Ponce-Gallegos et al. (2014) IINIT 2. Pagia Sagrah Structuring (2)

UNIT 2: Agents (2)

UNIT 3: Basic Search Strategies (2)		
Competences: a,j		
Content	Generales Goals	
 Problem spaces (states, goals and operators), problem solving by search Factored representation (factoring state into variables) Uninformed search (breadth-first, depth-first, depth-first with iterative deepening) Heuristics and informed search (hill-climbing, generic best-first, A*) Space and time efficiency of search Two-player games (introduction to minimax search) Constraint satisfaction (backtracking and local search methods) Readings: Nilsson (2001), Ponce-Gallegos et al. (2014) 	 Formulate an efficient problem space for a problem expressed in natural language (eg, English) in terms of initial and goal states, and operators [Usage] Describe the role of heuristics and describe the tradeoffs among completeness, optimality, time complexity, and space complexity [Usage] Describe the problem of combinatorial explosion of search space and its consequences [Usage] Compare and contrast basic search issues with game playing issues [Usage] 	
2001, 1 once denegos et al. (2011)		

Competences: a,j	
Content	Generales Goals
 Stochastic search Simulated annealing Genetic algorithms Monte-Carlo tree search Constructing search trees, dynamic search space, combinatorial explosion of search space Implementation of A* search, beam search Minimax search, alpha-beta pruning Expectimax search (MDP-solving) and chance nodes 	 Design and implement a genetic algorithm solution to a problem [Usage] Design and implement a simulated annealing schedule to avoid local minima in a problem [Usage] Design and implement A*,beam search to solve a problem [Usage] Apply minimax search with alpha-beta pruning to prune search space in a two-player game [Usage] Compare and contrast genetic algorithms with classic search techniques [Usage] Compare and contrast various heuristic searches visa-vis applicability to a given problem [Usage]
Readings: Goldberg (1989), Nilsson (2001), Russell and Norvig (2003), Ponce-Gallegos et al. (2014)	

UNIT 5: Reasoning Under Uncertainty (18)	
Competences: a,j	
Content	Generales Goals
 Review of basic probability Random variables and probability distributions Axioms of probability Probabilistic inference Bayes' Rule Conditional Independence Knowledge representations Bayesian Networks Exact inference and its complexity Randomized sampling (Monte Carlo) methods (e.g. Gibbs sampling) Markov Networks Relational probability models Hidden Markov Models 	 Apply Bayes' rule to determine the probability of a hypothesis given evidence [Usage] Explain how conditional independence assertions allow for greater efficiency of probabilistic systems [Usage] Identify examples of knowledge representations for reasoning under uncertainty [Usage] State the complexity of exact inference Identify methods for approximate inference [Usage]
Readings: Koller and Friedman (2009), Russell and Norvi	ig (2003)

UNIT 6: Basic Machine Learning (4) Competences: a,j Content Generales Goals • Definition and examples of broad variety of machine • List the differences among the three main styles of learning tasks, including classification learning: supervised, reinforcement, and unsupervised [Usage] • Inductive learning • Identify examples of classification tasks, including • Simple statistical-based learning, such as Naive the available input features and output to be pre-Bayesian Classifier, decision trees dicted [Usage] • The over-fitting problem • Explain the difference between inductive and deductive learning [Usage] Measuring classifier accuracy • Describe over-fitting in the context of a problem [Usage • Apply the simple statistical learning algorithm such as Naive Bayesian Classifier to a classification task and measure the classifier's accuracy [Usage] Readings: Mitchell (1998), Russell and Norvig (2003), Ponce-Gallegos et al. (2014)

UNIT 7: Advanced Machine Learning (20)		
Competences: a,j		
Content	Generales Goals	
 Definition and examples of broad variety of machine learning tasks General statistical-based learning, parameter estimation (maximum likelihood) Inductive logic programming (ILP) Supervised learning Learning decision trees 	 Explain the differences among the three main styles of learning: supervised, reinforcement, and unsupervised [Usage] Implement simple algorithms for supervised learning, reinforcement learning, and unsupervised learning [Usage] Determine which of the three learning styles is appropriate to a particular problem domain [Usage] 	
- Learning decision trees - Learning neural networks - Support vector machines (SVMs) • Unsupervised Learning and clustering	Compare and contrast each of the following techniques, providing examples of when each strategy is superior: decision trees, neural networks, and belief networks [Usage]	
 EM K-means Self-organizing maps 	 Evaluate the performance of a simple learning system on a real-world dataset [Usage] Characterize the state of the art in learning theory, 	
 Semi-supervised learning Learning graphical models Performance evaluation (such as cross-validation, area under ROC curve) 	 including its achievements and its shortcomings [Usage] Explain the problem of overfitting, along with techniques for detecting and managing the problem [Usage] 	
Application of Machine Learning algorithms to Data Mining (cross-reference IM/Data Mining)		

Readings: Russell and Norvig (2003), Koller and Friedman (2009), Murphy (2012)

mpetences: a,j	
ntent	Generales Goals
 Deterministic and stochastic grammars Parsing algorithms CFGs and chart parsers (e.g. CYK) Probabilistic CFGs and weighted CYK 	 Define and contrast deterministic and stochasti grammars, providing examples to show the adequacy of each [Usage] Simulate, apply, or implement classic and stochasti algorithms for parsing natural language [Usage]
 Representing meaning / Semantics Logic-based knowledge representations 	 algorithms for parsing natural language [Usage] Identify the challenges of representing meaning [Usage] List the advantages of using standard corpora Identify examples of current corpora for a variety of NLI tasks [Usage] Identify techniques for information retrieval, language translation, and text classification [Usage]
 Semantic roles Temporal representations Beliefs, desires, and intentions Corpus-based methods 	
 N-grams and HMMs Smoothing and backoff 	
• Examples of use: POS tagging and morphology	
 Information retrieval Vector space model * TF & IDF Precision and recall 	
• Information extraction	
• Language translation	
• Text classification, categorization	
 Bag of words model 	
adings: Nilsson (2001), Russell and Norvig (2003), P	ones Colleges et al. (2014)

Competences: a,j Content Generales Goals • Computer vision • Summarize the importance of image and object recognition in AI and indicate several significant ap-- Image acquisition, representation, processing plications of this technology [Usage] and properties • List at least three image-segmentation approaches, - Shape representation, object recognition and such as thresholding, edge-based and region-based segmentation algorithms, along with their defining characteristics, Motion analysis strengths, and weaknesses [Usage] • Modularity in recognition • Implement 2d object recognition based on contourand/or region-based shape representations [Usage] • Approaches to pattern recognition • Provide at least two examples of a transformation of - Classification algorithms and measures of clasa data source from one sensory domain to another, sification quality eg, tactile data interpreted as single-band 2d images - Statistical techniques [Usage] • Implement a feature-extraction algorithm on real data, eg, an edge or corner detector for images or vectors of Fourier coefficients describing a short slice of audio signal [Usage] • Implement a classification algorithm that segments input percepts into output categories and quantitatively evaluates the resulting classification [Usage] • Evaluate the performance of the underlying featureextraction, relative to at least one alternative possible approach (whether implemented or not) in its contribution to the classification task (8), above [Usage Readings: Nilsson (2001), Russell and Norvig (2003), Ponce-Gallegos et al. (2014)

8. Methodology

El profesor del curso presentará clases teóricas de los temas señalados en el programa propiciando la intervención de los alumnos.

El profesor del curso presentará demostraciones para fundamentar clases teóricas.

El profesor y los alumnos realizarán prácticas

UNIT 9: Perception and Computer Vision (12)

Los alumnos deberán asistir a clase habiendo leído lo que el profesor va a presentar. De esta manera se facilitará la comprensión y los estudiantes estarán en mejores condiciones de hacer consultas en clase.

9. Assessment

Continuous Assessment 1 : 20 %

Partial Exam: 30 %

Continuous Assessment 2: 20 %

Final exam : 30 %

References

 $\label{eq:castro} \mbox{De Castro, L.N. (2006)}. \ \emph{Fundamentals of natural computing: basic concepts, algorithms, and applications}. \ \mbox{CRC Press.}$

Goldberg, David (1989). Genetic Algorithms in Search, Optimization and Machine Learning. Addison Wesley.

Koller, Daphne and Nir Friedman (2009). Probabilistic Graphical Models: Principles and Techniques - Adaptive Computation and Machine Learning. The MIT Press. ISBN: 0262013193.

Mitchell, M. (1998). An introduction to genetic algorithms. The MIT press.

Murphy, Kevin P. (2012). Machine Learning: A Probabilistic Perspective. The MIT Press. ISBN: 0262018020.

Nilsson, Nils (2001). Inteligencia Artificial: Una nueva visión. McGraw-Hill.

Ponce-Gallegos, Julio et al. (2014). *Inteligencia Artificial*. Iniciativa Latinoamericana de Libros de Texto Abiertos (LATIn). Russell, Stuart and Peter Norvig (2003). *Inteligencia Artifical: Un enfoque moderno*. Prentice Hall.